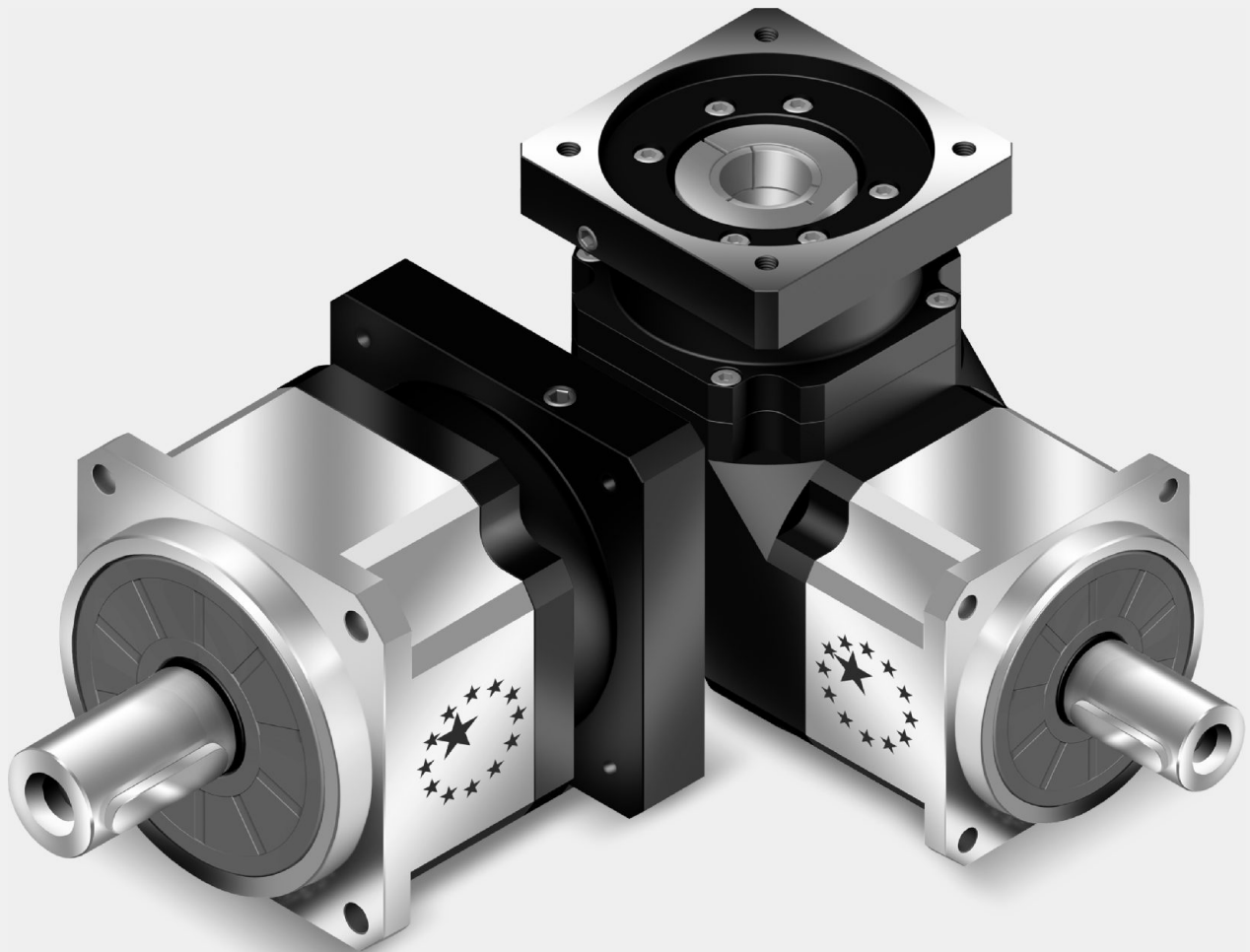




APEX DYNAMICS, INC.

**HIGH PRECISION
PLANETARY GEARBOX**

AB / ABR Series



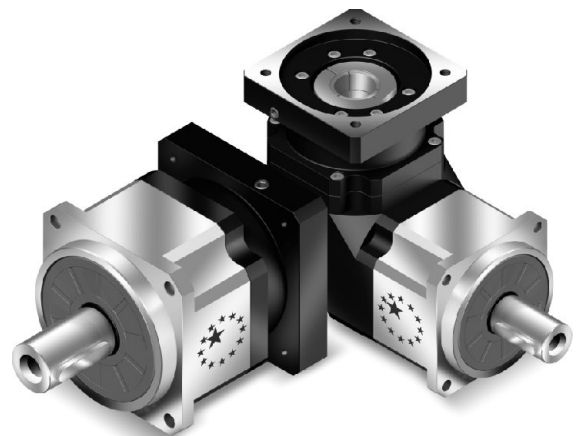
Stainless



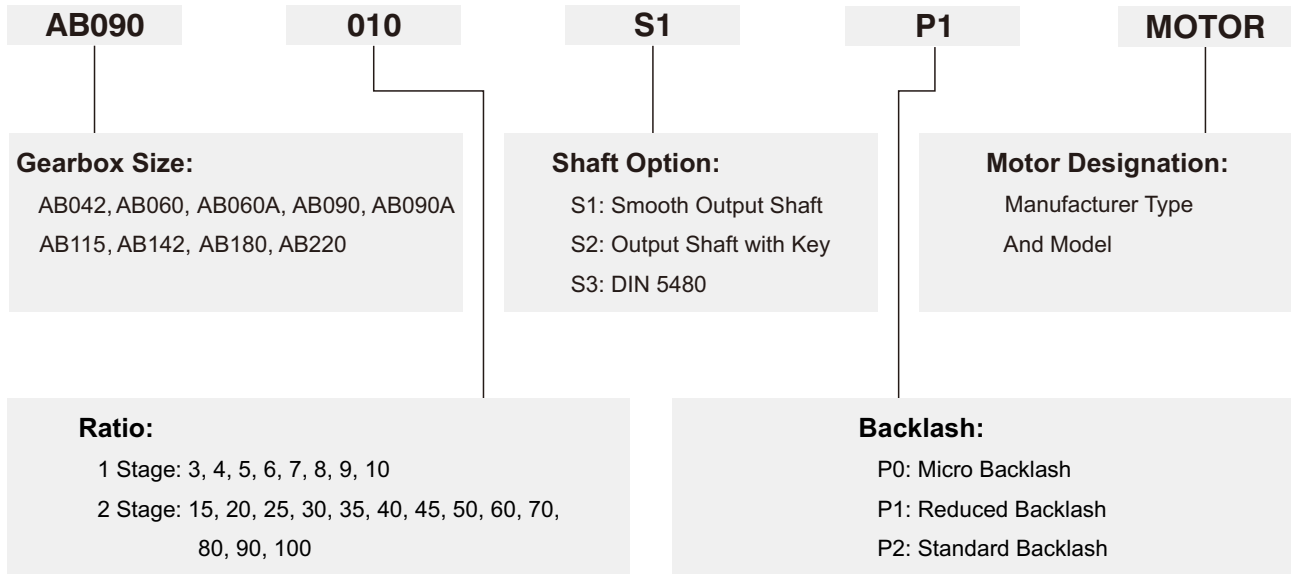
Apex Dynamics, Inc. is the world's most productive manufacturer of servomotor drive planetary gearboxes for precision automation machinery. From our 800,000+ square foot ISO 9001:2008 manufacturing facility, based in Taichung, Taiwan, we manufacture to stock using the newest precision machine tools and quality test and inspection equipment. Complete focus on quality and precision allows us to produce our high quality gearheads at precision levels down to less than 1 arc minute (1/60 th of a degree), with consistency and high reliability.

Based on more than twenty years of accumulated manufacturing and marketing experience, plus the highest level of technical production capabilities, Apex Dynamics, Inc. designs and builds technically advanced, high speed, low backlash servo application planetary gearboxes. Our Break through patented technology (over 6 patents), provides the customer with the optimum high precision helical reducer at a reasonable price. We are continuously improving processes, finding proper and effective methods to provide customers new solutions for difficult applications, and developing new products.

The primary focus in daily operation is quality. We pride ourselves on our dedication to quality; our duty - is customer satisfaction.

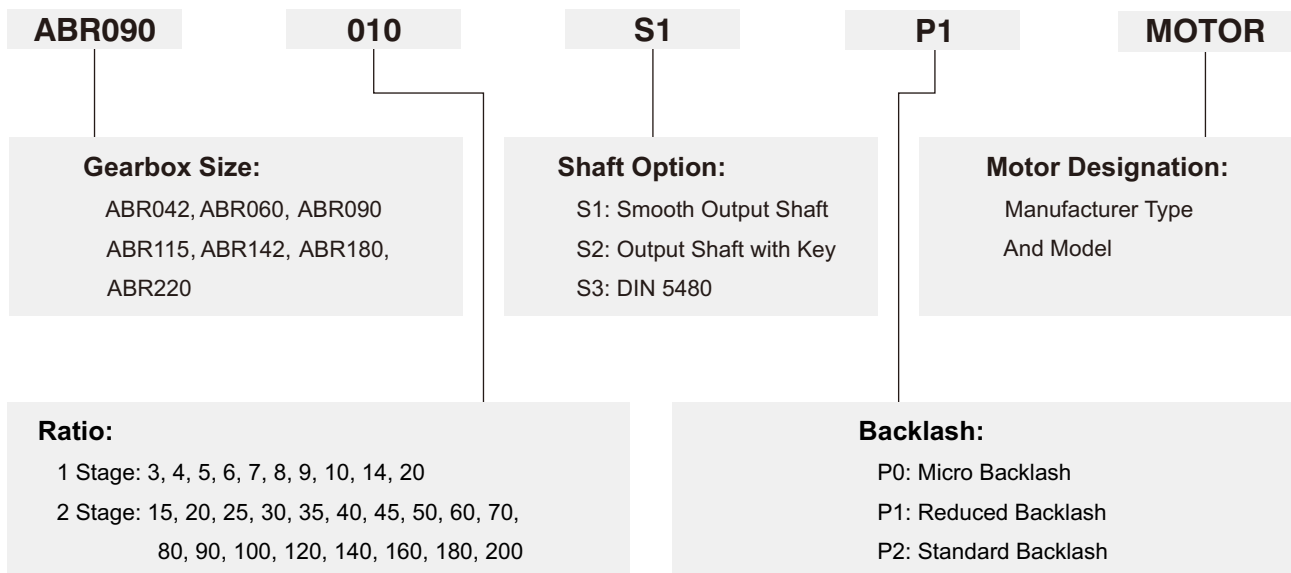


AB Series



Ordering Example: AB090-010-S1-P1 / SIEMENS 1FT6 041-4AF71

ABR Series



Ordering Example: ABR090-010-S1-P1 / SIEMENS 1FT6 041-4AF71

Specifications / AB Series

Gearbox Performance

Model No.		Stage	Ratio ^A	AB042	AB060	AB060A	AB090	AB090A	AB115	AB142	AB180	AB220
Nominal Output Torque T_{2N}	Nm	1	3	20	55	–	130	–	208	342	588	1,140
			4	19	50	–	140	–	290	542	1,050	1,700
			5	22	60	–	160	–	330	650	1,200	2,000
			6	20	55	–	150	–	310	600	1,100	1,900
			7	19	50	–	140	–	300	550	1,100	1,800
			8	17	45	–	120	–	260	500	1,000	1,600
			9	14	40	–	100	–	230	450	900	1,500
		2	10	14	40	–	100	–	230	450	900	1,500
			15	20	55	55	130	130	208	342	588	1,140
			20	19	50	50	140	140	290	542	1,050	1,700
			25	22	60	60	160	160	330	650	1,200	2,000
			30	20	55	55	150	150	310	600	1,100	1,900
			35	19	50	50	140	140	300	550	1,100	1,800
			40	17	45	45	120	120	260	500	1,000	1,600
			45	14	40	40	100	100	230	450	900	1,500
			50	22	60	60	160	160	330	650	1,200	2,000
			60	20	55	55	150	150	310	600	1,100	1,900
			70	19	50	50	140	140	300	550	1,100	1,800
80	17	45	45	120	120	260	500	1,000	1,600			
90	14	40	40	100	100	230	450	900	1,500			
100	14	40	40	100	100	230	450	900	1,500			
Emergency Stop Torque T_{2NOT}^B	Nm	1,2	3~100	3 times of Nominal Output Torque								
Nominal Input Speed n_{1N}	rpm	1,2	3~100	5,000	5,000	5,000	4,000	4,000	4,000	3,000	3,000	2,000
Max. Input Speed n_{1B}	rpm	1,2	3~100	10,000	10,000	10,000	8,000	8,000	8,000	6,000	6,000	4,000
Micro Backlash P0	arcmin	1	3~10	–	–	–	≤1	–	≤1	≤1	≤1	≤1
		2	15~100	–	–	–	–	–	≤3	≤3	≤3	≤3
Reduced Backlash P1	arcmin	1	3~10	≤3	≤3	–	≤3	–	≤3	≤3	≤3	≤3
		2	15~100	≤5	≤5	≤5	≤5	≤5	≤5	≤5	≤5	≤5
Standard Backlash P2	arcmin	1	3~10	≤5	≤5	–	≤5	–	≤5	≤5	≤5	≤5
		2	15~100	≤7	≤7	≤7	≤7	≤7	≤7	≤7	≤7	≤7
Torsional Rigidity	Nm/arcmin	1,2	3~100	3	7	7	14	14	25	50	145	225
Max. Radial Load F_{2rB}^C	N	1,2	3~100	780	1,530	1,530	3,250	3,250	6,700	9,400	14,500	50,000
Max. Axial Load F_{2aB}^C	N	1,2	3~100	390	765	765	1,625	1,625	3,350	4,700	7,250	25,000
Service Life ^D	hr	1,2	3~100	20,000								
Efficiency η	%	1	3~10	≥97%								
		2	15~100	≥94%								
Weight	kg	1	3~10	0.6	1.3	–	3.7	–	7.8	14.5	29	48
		2	15~100	0.8	1.5	1.9	4.1	5.3	9	17.5	33	60
Operating Temp	°C	1,2	3~100	-10°C~90°C								
Lubrication				Synthetic lubrication oils								
Degree of Gearbox Protection		1,2	3~100	IP65								
Mounting Position		1,2	3~100	all directions								
Noise ($n_1=3000\text{rpm}$, $i=10$, No load) ^E	dB(A)	1,2	3~100	≤56	≤58	≤60	≤60	≤63	≤63	≤65	≤67	≤70

Gearbox Inertia

Model No.		Stage	Ratio ^A	AB042	AB060	AB060A	AB090	AB090A	AB115	AB142	AB180	AB220
Mass Moments of Inertia J_1	kg · cm ²	1	3	0.03	0.16	–	0.61	–	3.25	9.21	28.98	69.61
			4	0.03	0.14	–	0.48	–	2.74	7.54	23.67	54.37
			5	0.03	0.13	–	0.47	–	2.71	7.42	23.29	53.27
			6	0.03	0.13	–	0.45	–	2.65	7.25	22.75	51.72
			7	0.03	0.13	–	0.45	–	2.62	7.14	22.48	50.97
			8	0.03	0.13	–	0.44	–	2.58	7.07	22.59	50.84
			9	0.03	0.13	–	0.44	–	2.57	7.04	22.53	50.63
		2	10	0.03	0.13	–	0.44	–	2.57	7.03	22.51	50.56
			15	0.03	0.03	0.13	0.13	0.47	0.47	2.71	7.42	23.29
			20	0.03	0.03	0.13	0.13	0.47	0.47	2.71	7.42	23.29
			25	0.03	0.03	0.13	0.13	0.47	0.47	2.71	7.42	23.29
			30	0.03	0.03	0.13	0.13	0.47	0.47	2.71	7.42	23.29
			35	0.03	0.03	0.13	0.13	0.47	0.47	2.71	7.42	23.29
			40	0.03	0.03	0.13	0.13	0.47	0.47	2.71	7.42	23.29
			45	0.03	0.03	0.13	0.13	0.47	0.47	2.71	7.42	23.29
			50	0.03	0.03	0.13	0.13	0.44	0.44	2.57	7.03	22.51
			60	0.03	0.03	0.13	0.13	0.44	0.44	2.57	7.03	22.51
			70	0.03	0.03	0.13	0.13	0.44	0.44	2.57	7.03	22.51
80	0.03	0.03	0.13	0.13	0.44	0.44	2.57	7.03	22.51			
90	0.03	0.03	0.13	0.13	0.44	0.44	2.57	7.03	22.51			
100	0.03	0.03	0.13	0.13	0.44	0.44	2.57	7.03	22.51			

A. Ratio ($i=N_n/N_{out}$)B. Max. acceleration torque $T_{2B} = 60\%$ of T_{2NOT}

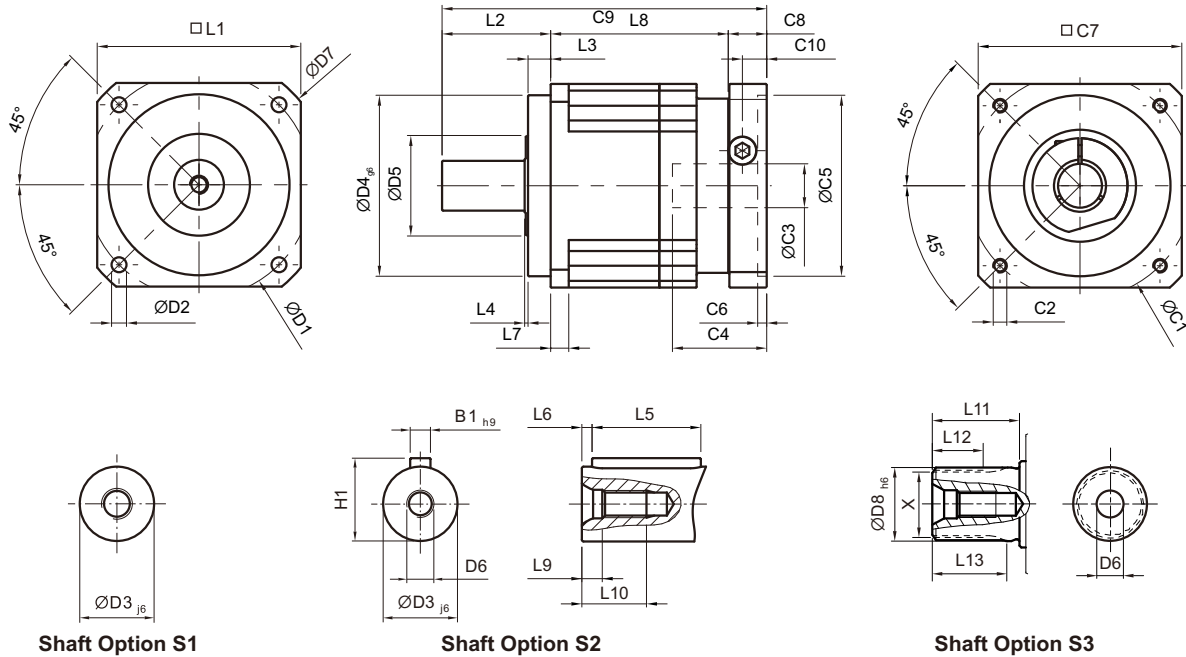
C. Applied to the output shaft center at 100 rpm

D. For continuous operation, the service life time is less than 10,000hrs

E. These values are measured by gearbox with ratio = 10 (1-stage) or ratio = 100 (2-stage) at 3,000 rpm without load.

By ratio smaller than 10, the noise value would be 3-5dB higher

Dimensions (1-stage, Ratio $i=3\sim 10$) / AB Series

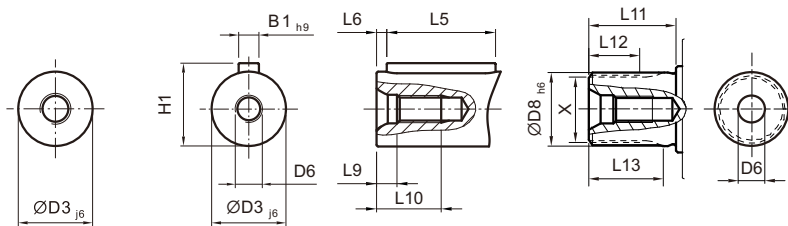
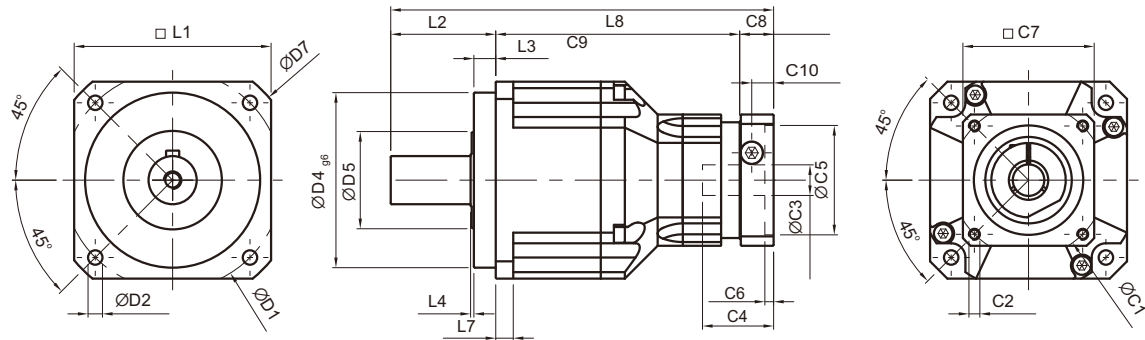


[unit: mm]

Dimension	AB042	AB060	AB090	AB115	AB142	AB180	AB220
D1	50	70	100	130	165	215	250
D2	3.4	5.5	6.6	9	11	13	17
D3 _{j6}	13	16	22	32	40	55	75
D4 _{g6}	35	50	80	110	130	160	180
D5	22	45	65	95	75	95	115
D6	M4 x 0.7P	M5 x 0.8P	M8 x 1.25P	M12 x 1.75P	M16 x 2P	M20 x 2.5P	M20 x 2.5P
D7	56	80	116	152	185	240	292
D8 _{h6}	-	16	22	32	40	55	75
L1	42	60	90	115	142	180	220
L2	26	37	48	65	97	105	138
L3	5.5	7	10	12	15	20	30
L4	1	1.5	1.5	2	3	3	3
L5	16	25	32	40	63	70	90
L6	2	2	3	5	5	6	7
L7	4	6	8	10	12	15	20
L8	31	61	78.5	102	119.5	154	163.5
L9	4.5	4.8	7.2	10	12	15	15
L10	10	12.5	19	28	36	42	42
L11	-	26	26	26	40	41.5	52
L12	-	15	15	15	20	21.5	28
L13	-	21	22.5	23	33.5	33.5	45
C1 ¹	46	70	100	130	165	215	235
C2 ¹	M4 x 0.7P	M5 x 0.8P	M6 x 1P	M8 x 1.25P	M10 x 1.5P	M12 x 1.75P	M12 x 1.75P
C3 ¹	≤11 / ≤12 ²	≤14 / ≤16 ²	≤19 / ≤24	≤32	≤38	≤48	≤55
C4 ¹	25	34	40	50	60	85	116
C5 ¹	30	50	80	110	130	180	200
C6 ¹	3.5	8	4	5	6	6	6
C7 ¹	42	60	90	115	142	190	220
C8 ¹	29.5	19	17	19.5	22.5	29	63
C9 ¹	86.5	117	143.5	186.5	239	288	364.5
C10 ¹	8.75	13.5	10.75	13	15	20.75	53
B1 _{h9}	5	5	6	10	12	16	20
H1	15	18	24.5	35	43	59	79.5
X DIN5480	-	W16x0.8x 30x18x6m	W22x1.25x 30x16x6m	W32x1.25x 30x24x6m	W40x2x 30x18x6m	W55x2x 30x26x6m	W70x2x 30x34x6m

1. C1~C10 are motor specific dimensions (metric std shown). Refer to www.apexdyna.com and Design Tool to view your specific motor mounting system.
 2. AB042 ratio 5, 10 offers C3 ≤ 12 option; AB060 ratio 5, 10 offers C3 ≤ 16 option.

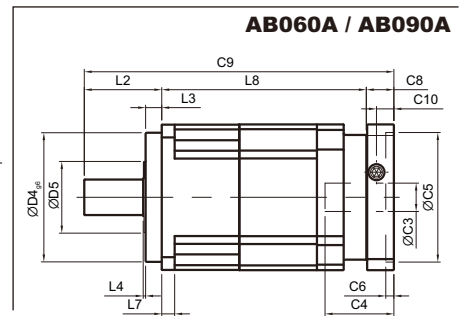
Dimensions (2-stage, Ratio $i = 15 \sim 100$) / AB Series



Shaft Option S1

Shaft Option S2

Shaft Option S3



AB060A / AB090A

[unit: mm]

Dimension	AB042	AB060	AB060A	AB090	AB090A	AB115	AB142	AB180	AB220
D1	50	70		100		130	165	215	250
D2	3.4	5.5		6.6		9	11	13	17
D3 _{j6}	13	16		22		32	40	55	75
D4 _{g6}	35	50		80		110	130	160	180
D5	22	45		65		95	75	95	115
D6	M4 x 0.7P	M5 x 0.8P		M8 x 1.25P		M12 x 1.75P	M16 x 2P	M20 x 2.5P	M20 x 2.5P
D7	56	80		116		152	185	240	292
D8 _{h6}	-	16		22		32	40	55	75
L1	42	60		90		115	142	180	220
L2	26	37		48		65	97	105	138
L3	5.5	7		10		12	15	20	30
L4	1	1.5		1.5		2	3	3	3
L5	16	25		32		40	63	70	90
L6	2	2		3		5	5	6	7
L7	4	6		8		10	12	15	20
L8	58.5	72	98	111.5	126.5	143.5	176	209.5	248
L9	4.5	4.8		7.2		10	12	15	15
L10	10	12.5		19		28	36	42	42
L11	-	26		26		26	40	41.5	52
L12	-	15		15		15	20	21.5	28
L13	-	21		22.5		23	33.5	33.5	45
C1 ³	46	46	70	70	100	100	130	165	215
C2 ³	M4 x 0.7P	M4 x 0.7P	M5 x 0.8P	M5 x 0.8P	M6 x 1P	M6 x 1P	M8 x 1.25P	M10 x 1.5P	M12 x 1.75P
C3 ³	≤11 / ≤12	≤11 / ≤12	≤14 / ≤16	≤14 / ≤15.875 / ≤16	≤19 / ≤24	≤19 / ≤24	≤32	≤38	≤48
C4 ³	25	25	34	34	40	40	50	60	85
C5 ³	30	30	50	50	80	80	110	130	180
C6 ³	3.5	3.5	8	8	4	4	5	6	6
C7 ³	42	42	60	60	90	90	115	142	190
C8 ³	29.5	29.5	19	19	17	17	19.5	22.5	29
C9 ³	114	138.5	154	178.5	191.5	225.5	292.5	337	415
C10 ³	8.75	8.75	13.5	13.5	10.75	10.75	13	15	20.75
B1 _{h9}	5	5		6		10	12	16	20
H1	15	18		24.5		35	43	59	79.5
X DIN5480	-	W16x0.8x 30x18x6m		W22x1.25x 30x16x6m		W32x1.25x 30x24x6m	W40x2x 30x18x6m	W55x2x 30x26x6m	W70x2x 30x34x6m

3. C1-C10 are motor specific dimensions (metric std shown). Refer to www.apexdyna.com and Design Tool to view your specific motor mounting system.

Specifications / ABR Series

Gearbox Performance

Model No.	Stage	Ratio ^A	ABR042	ABR060	ABR090	ABR115	ABR142	ABR180	ABR220	
Nominal Output Torque T_{2N}	1	3	9	36	90	195	342	588	1,140	
		4	12	48	120	260	520	1,040	1,680	
		5	15	60	150	325	650	1,200	2,000	
		6	18	55	150	310	600	1,100	1,900	
		7	19	50	140	300	550	1,100	1,800	
		8	17	45	120	260	500	1,000	1,600	
		9	14	40	100	230	450	900	1,500	
		10	14	60	150	325	650	1,200	2,000	
		14	-	42	140	300	550	1,100	1,800	
		20	-	40	100	230	450	900	1,500	
	2	15	14	-	-	-	-	-	-	-
		20	14	-	-	-	-	-	-	-
		25	15	60	150	325	650	1,200	2,000	
		30	20	55	150	310	600	1,100	1,900	
		35	19	50	140	300	550	1,100	1,800	
		40	17	45	120	260	500	1,000	1,600	
		45	14	40	100	230	450	900	1,500	
		50	14	60	100	230	650	1,200	2,000	
		60	20	55	150	310	600	1,100	1,900	
		70	19	50	140	300	550	1,100	1,800	
80	17	45	120	260	500	1,000	1,600			
90	14	40	100	230	450	900	1,500			
100	14	40	100	230	450	900	1,500			
120	-	-	150	310	600	1,100	1,900			
140	-	-	140	300	550	1,100	1,800			
160	-	-	120	260	550	1,000	1,600			
180	-	-	100	230	450	900	1,500			
200	-	-	100	230	450	900	1,500			
Emergency Stop Torque T_{2NOT} ^B	Nm	1,2	3 times of Nominal Output Torque							
Nominal Input Speed n_{1N}	rpm	1,2	3~200	5,000	5,000	4,000	4,000	3,000	3,000	2,000
Max. Input Speed n_{1B}	rpm	1,2	3~200	10,000	10,000	8,000	8,000	6,000	6,000	4,000
Micro Backlash P0	arcmin	1	3~20	-	-	≤2	≤2	≤2	≤2	≤2
		2	25~200	-	-	≤4	≤4	≤4	≤4	≤4
Reduced Backlash P1	arcmin	1	3~20	≤4	≤4	≤4	≤4	≤4	≤4	≤4
		2	25~200	≤7	≤7	≤7	≤7	≤7	≤7	≤7
Standard Backlash P2	arcmin	1	3~20	≤6	≤6	≤6	≤6	≤6	≤6	≤6
		2	25~200	≤9	≤9	≤9	≤9	≤9	≤9	≤9
Torsional Rigidity	Nm/arcmin	1,2	3~200	3	7	14	25	50	145	225
Max. Radial Load F_{2RB} ^C	N	1,2	3~200	780	1,530	3,250	6,700	9,400	14,500	50,000
Max. Axial Load F_{2AB} ^C	N	1,2	3~200	390	765	1,625	3,350	4,700	7,250	25,000
Service Life ^D	hr	1,2	3~200	20,000						
Efficiency η	%	1	3~20	≥95%						
		2	25~200	≥92%						
Weight	kg	1	3~20	0.9	2.1	6.4	13	24.5	51	83
		2	25~200	1.2	1.5	7.8	14.2	27.5	54	95
Operating Temp	°C	1,2	3~200	-10°C~+90°C						
Lubrication				Synthetic lubrication oils						
Degree of Gearbox Protection		1,2	3~200	IP65						
Mounting Position		1,2	3~200	all directions						
Noise ($n_1=3000$ rpm, $i=10$, No load) ^E	dB(A)	1,2	3~200	≤61	≤63	≤65	≤68	≤70	≤72	≤74

Gearbox Inertia

Model No.	Stage	Ratio ^A	ABR042	ABR060	ABR090	ABR115	ABR142	ABR180	ABR220
Mass Moments of Inertia J , kg · cm ²	1	3~10	0.09	0.35	2.25	6.84	23.4	68.9	135.4
		14	-	0.07	1.87	6.25	21.8	65.6	119.8
		20	-	0.07	1.87	6.25	21.8	65.6	119.8
	2	15	0.09	-	-	-	-	-	-
		20	0.09	-	-	-	-	-	-
		25~100	0.09	0.09	0.35	2.25	6.84	23.4	68.9
120~200	-	-	0.31	1.87	6.25	21.8	65.6		

A. Ratio ($i=N_{in}/N_{out}$)

B. Max. acceleration torque $T_{2B} = 60\%$ of T_{2NOT}

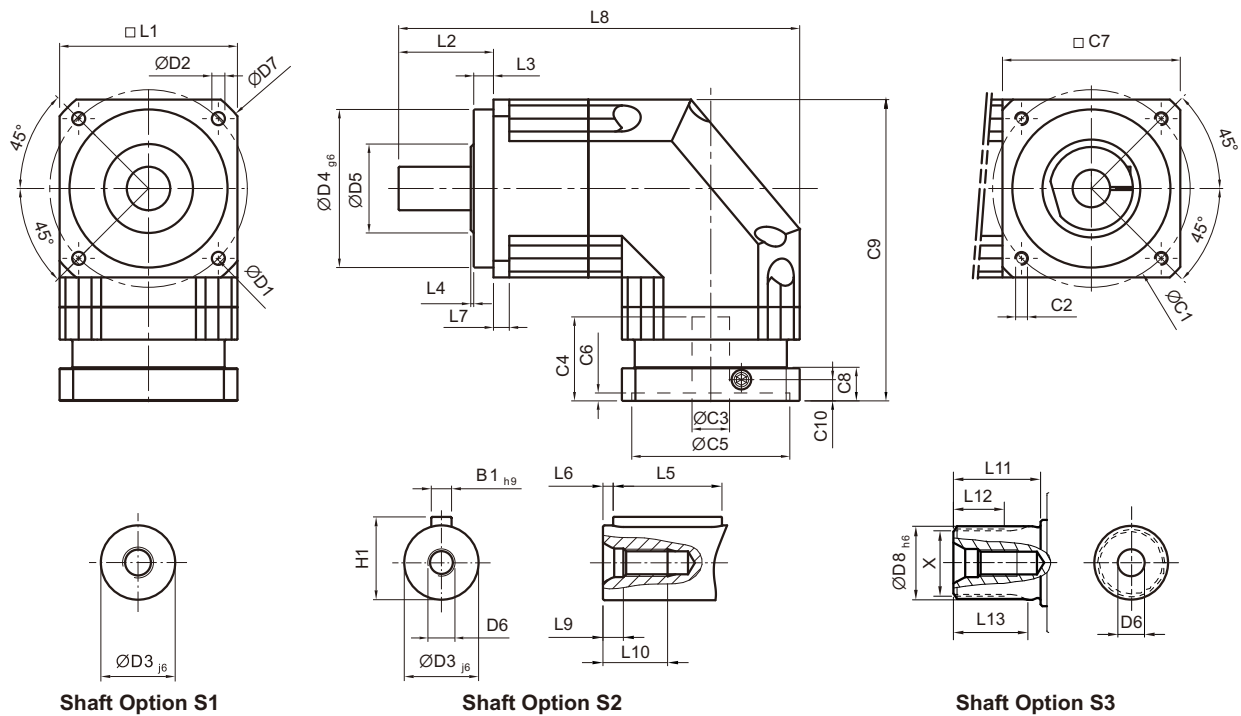
C. Applied to the output shaft center at 100 rpm

D. For continuous operation, the service life time is less than 10,000hrs

E. These values are measured by gearbox with ratio = 10 (1-stage) or ratio = 100 (2-stage) at 3,000 rpm without load.

By ratio smaller than 10, the noise value would be 3-5dB higher

Dimensions (1-stage, Ratio $i=3\sim 20$) / ABR Series

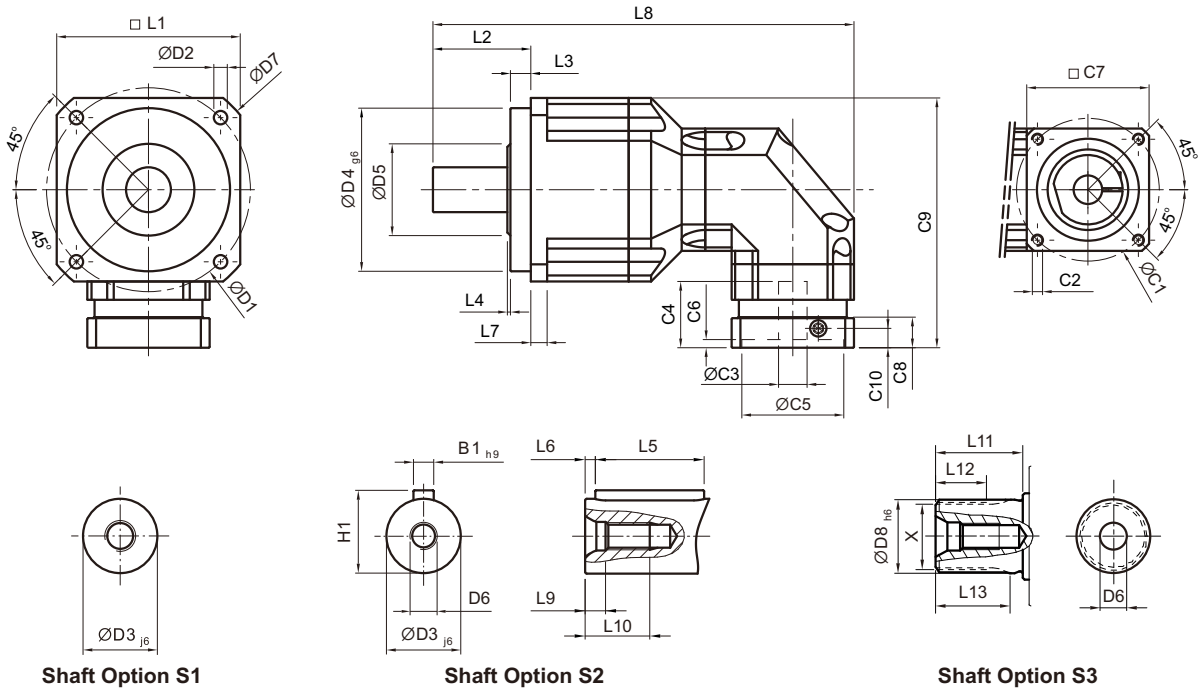


[unit: mm]

Dimension	ABR042	ABR060	ABR090	ABR115	ABR142	ABR180	ABR220
D1	50	70	100	130	165	215	250
D2	3.4	5.5	6.6	9	11	13	17
D3 _{j6}	13	16	22	32	40	55	75
D4 _{g6}	35	50	80	110	130	160	180
D5	22	45	65	95	75	95	115
D6	M4 x 0.7P	M5 x 0.8P	M8 x 1.25P	M12 x 1.75P	M16 x 2P	M20 x 2.5P	M20 x 2.5P
D7	56	80	116	152	185	240	292
D8 _{h6}	-	16	22	32	40	55	75
L1	42	60	90	115	142	180	220
L2	26	37	48	65	97	105	138
L3	5.5	7	10	12	15	20	30
L4	1	1.5	1.5	2	3	3	3
L5	16	25	32	40	63	70	90
L6	2	2	3	5	5	6	7
L7	4	6	8	10	12	15	20
L8	111.5	145	203	259	333	394	484
L9	4.5	4.8	7.2	10	12	15	15
L10	10	12.5	19	28	36	42	42
L11	-	26	26	26	40	41.5	52
L12	-	15	15	15	20	21.5	28
L13	-	21	22.5	23	33.5	33.5	45
C1 ¹	46	70	100	130	165	215	235
C2 ¹	M4 x 0.7P	M5 x 0.8P	M6 x 1P	M8 x 1.25P	M10 x 1.5P	M12 x 1.75P	M12 x 1.75P
C3 ¹	≤11 / ≤12	≤14 / ≤16	≤19 / ≤24	≤32	≤38	≤48	≤55
C4 ¹	25	34	40	50	60	85	116
C5 ¹	30	50	80	110	130	180	200
C6 ¹	3.5	8	4	5	6	6	6
C7 ¹	42	60	90	115	142	190	220
C8 ¹	29.5	19	17	19.5	22.5	29	63
C9 ¹	90.5	111.5	152.5	191.5	235.5	303.5	378.5
C10 ¹	8.75	13.5	10.75	13	15	20.75	53
B1 _{h9}	5	5	6	10	12	16	20
H1	15	18	24.5	35	43	59	79.5
X DIN5480	-	W16x0.8x 30x18x6m	W22x1.25x 30x16x6m	W32x1.25x 30x24x6m	W40x2x 30x18x6m	W55x2x 30x26x6m	W70x2x 30x34x6m

1. C1~C10 are motor specific dimensions (metric std shown). Refer to www.apexdyna.com and Design Tool to view your specific motor mounting system.

Dimensions (2-stage, Ratio $i=15\sim 200$) / ABR Series



Shaft Option S1

Shaft Option S2

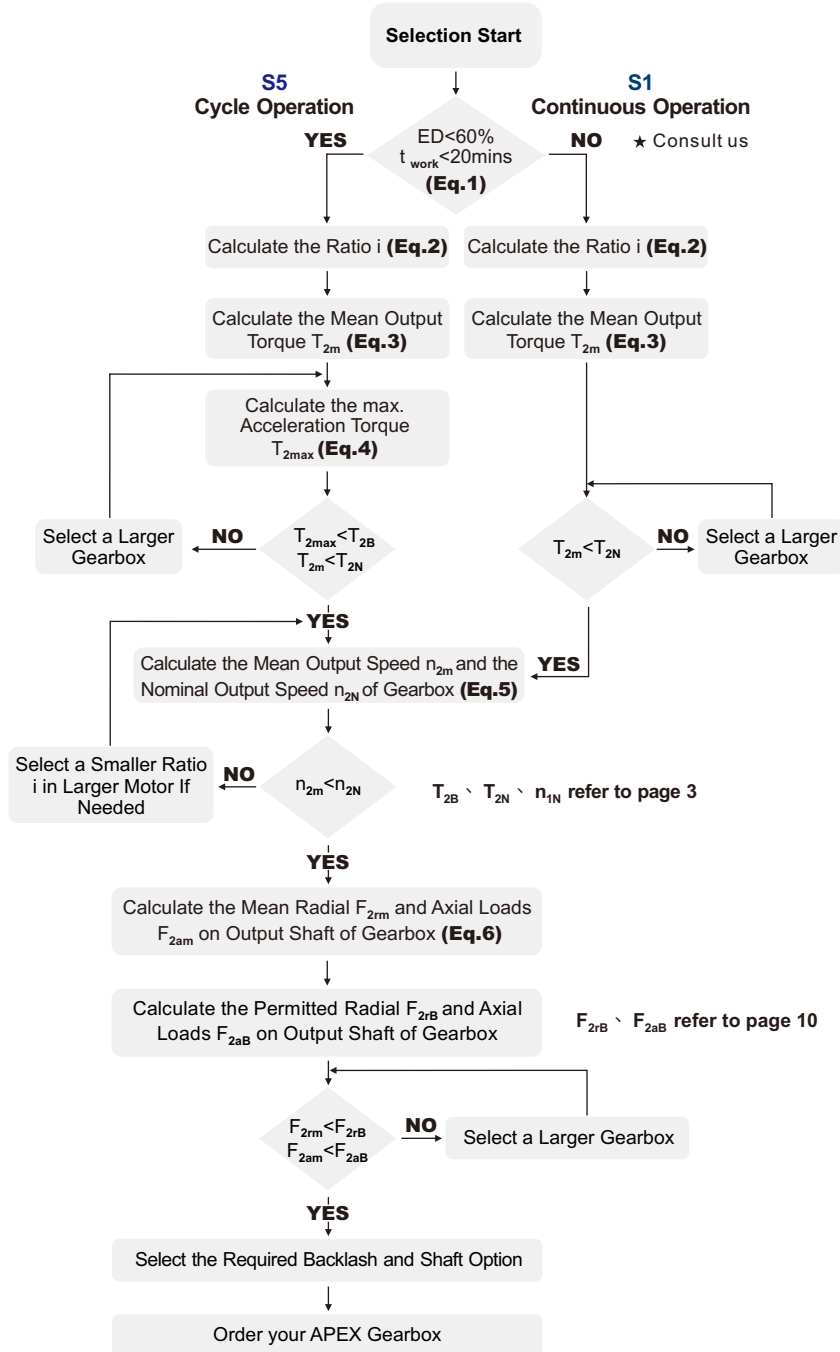
Shaft Option S3

[unit: mm]

Dimension	ABR042	ABR060	ABR090	ABR115	ABR142	ABR180	ABR220
D1	50	70	100	130	165	215	250
D2	3.4	5.5	6.6	9	11	13	17
D3 _{j6}	13	16	22	32	40	55	75
D4 _{g6}	35	50	80	110	130	160	180
D5	22	45	65	95	75	95	115
D6	M4 x 0.7P	M5 x 0.8P	M8 x 1.25P	M12 x 1.75P	M16 x 2P	M20 x 2.5P	M20 x 2.5P
D7	56	80	116	152	185	240	292
D8 _{h6}	-	16	22	32	40	55	75
L1	42	60	90	115	142	180	220
L2	26	37	48	65	97	105	138
L3	5.5	7	10	12	15	20	30
L4	1	1.5	1.5	2	3	3	3
L5	16	25	32	40	63	70	90
L6	2	2	3	5	5	6	7
L7	4	6	8	10	12	15	20
L8	139	163.5	206.5	285	365	431	521
L9	4.5	4.8	7.2	10	12	15	15
L10	10	12.5	19	28	36	42	42
L11	-	26	26	26	40	41.5	52
L12	-	15	15	15	20	21.5	28
L13	-	21	22.5	23	33.5	33.5	45
C1 ¹	46	46	70	100	130	165	215
C2 ¹	M4 x 0.7P	M4 x 0.7P	M5 x 0.8P	M6 x 1P	M8 x 1.25P	M10 x 1.5P	M12 x 1.75P
C3 ¹	≤11 / ≤12	≤11 / ≤12	≤14 / ≤15.875 / ≤16	≤19 / ≤24	≤32	≤38	≤48
C4 ¹	25	25	34	40	50	60	85
C5 ¹	30	30	50	80	110	130	180
C6 ¹	3.5	3.5	8	4	5	6	6
C7 ¹	42	42	60	90	115	142	190
C8 ¹	29.5	29.5	19	17	19.5	22.5	29
C9 ¹	90.5	99.5	126.5	165	205	254.5	323.5
C10 ¹	8.75	8.75	13.5	10.75	13	15	20.75
B1 _{h9}	5	5	6	10	12	16	20
H1	15	18	24.5	35	43	59	79.5
X DIN5480	-	W16x0.8x 30x18x6m	W22x1.25x 30x16x6m	W32x1.25x 30x24x6m	W40x2x 30x18x6m	W55x2x 30x26x6m	W70x2x 30x34x6m

2. C1~C10 are motor specific dimensions (metric std shown). Refer to www.apexdyna.com and Design Tool to view your specific motor mounting system.

Selection of the Optimum Gearbox



Recommended (for S5 Cycle Operation)

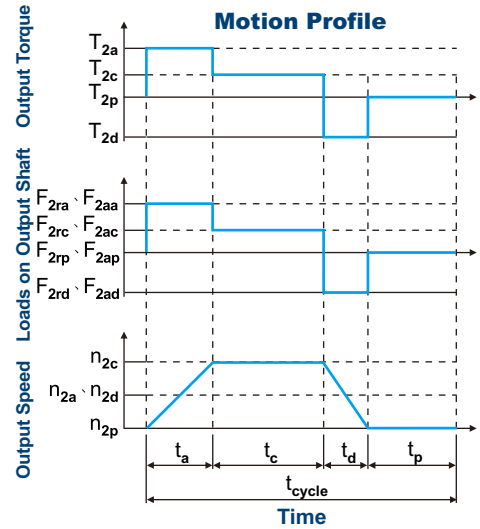
The general design is given for

$$\frac{J_L}{i^2} \leq 4 \times J_m$$

The optimal design is given for

$$\frac{J_L}{i^2} \cong J_m$$

J_L Load Inertia
 J_m Motor Inertia



$$1. ED = \frac{t_a + t_c + t_d}{t_{cycle}} \times 100\%, t_{work} = t_a + t_c + t_d$$

Index : a. Acceleration, c. Constant, d. Deceleration, p. Pause (Eq.1)

$$2. i \cong \frac{n_m}{n_{work}}$$

n_m Output Speed of the Motor
 n_{work} Working Speed (Eq.2)

$$3. T_{2m} = \sqrt[3]{\frac{n_{2a} \times t_a \times T_{2a}^3 + n_{2c} \times t_c \times T_{2c}^3 + n_{2d} \times t_d \times T_{2d}^3}{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}}$$

(Eq.3)

$$4. T_{2max} = T_{mB} \times i \times k_s \times \eta$$

where K_s is

K_s	No. of Cycles / hr
1.0	0 ~ 1,000
1.1	1,000 ~ 1,500
1.3	1,500 ~ 2,000
1.6	2,000 ~ 3,000
1.8	3,000 ~ 5,000

T_{mB} Max. Output Torque of the Motor
 η Efficiency of the Gearbox (Eq.4)

$$5. n_{2a} = n_{2d} = \frac{1}{2} \times n_{2c}$$

$$n_{2m} = \frac{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}{t_a + t_c + t_d}$$

$$n_{2N} = \frac{n_{1N}}{i}$$

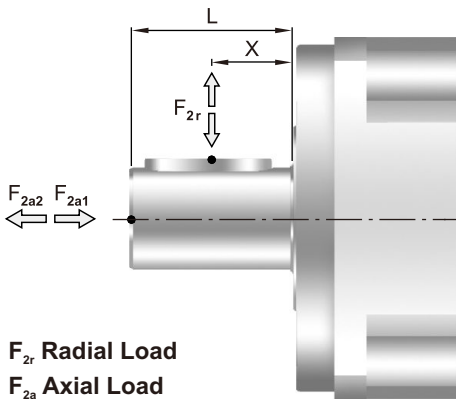
(Eq.5)

$$6. F_{2rm} = \sqrt[3]{\frac{n_{2a} \times t_a \times F_{2ra}^3 + n_{2c} \times t_c \times F_{2rc}^3 + n_{2d} \times t_d \times F_{2rd}^3}{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}}$$

$$F_{2am} = \sqrt[3]{\frac{n_{2a} \times t_a \times F_{2aa}^3 + n_{2c} \times t_c \times F_{2ac}^3 + n_{2d} \times t_d \times F_{2ad}^3}{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}}$$

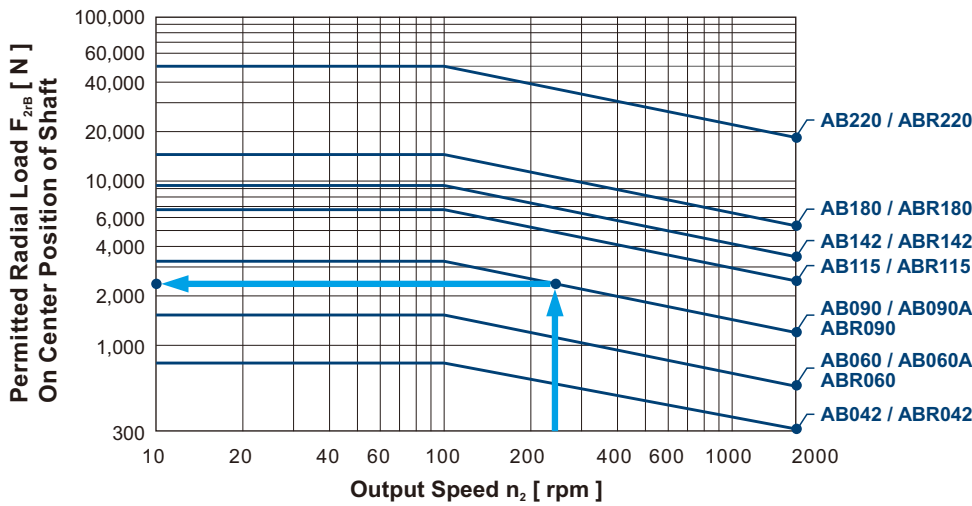
(Eq.6)

Permitted Radial and Axial Loads

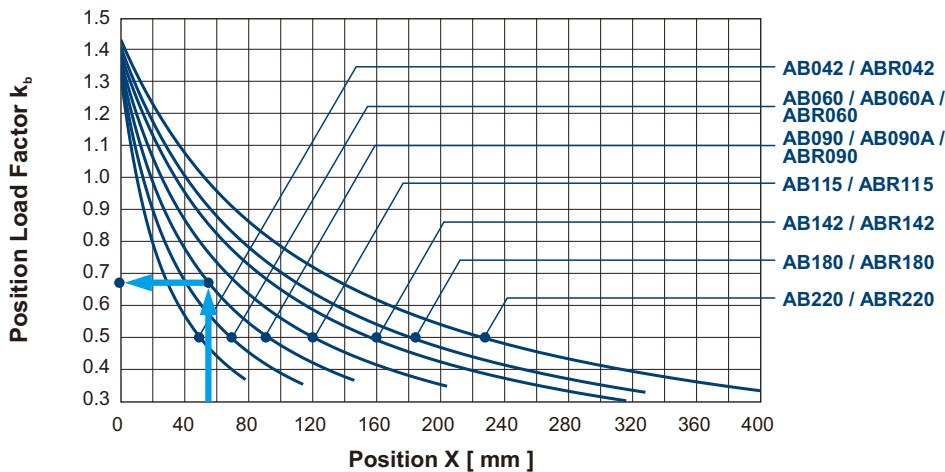


The permitted radial and axial loads on output shaft of the gearbox depend on the design of the gearbox supporting bearings. APEX use the extension straddle oversized ball bearing design. It can take heavy load from both axes.

F_{2r} Radial Load
 F_{2a} Axial Load



If radial force F_{2r} exert on the center of the output shaft $X=1/2 \times L$. Under various operating condition the lifetime is over 20,000* hours. The permitted radial load is given on left diagram.



If radial force F_{2r} not exert on the center of the output shaft $X < 1/2 \times L$ or $X > 1/2 \times L$. The permitted radial and axial load can be calculated by the position load factor k_b on the left diagram.

* S1 service life 10,000 hrs



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